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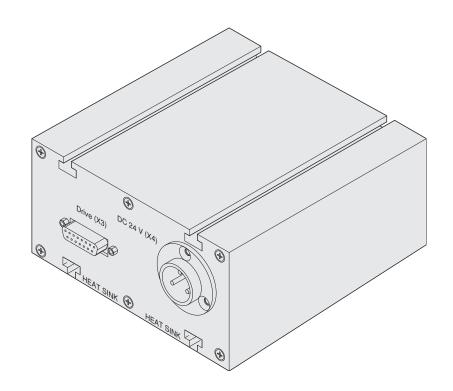
# TURBO.DRIVE 400

Frequency Converter for Turbomolecular Pumps

Operating Instructions 17200492\_002\_A5

Part Numbers

800073V0002 800073V0003 800073V0004 800073V0008



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#### **Obligation to Provide Information**

Before installing and commissioning the TURBO.DRIVE, carefully read these Operating Instructions and follow the information so as to ensure optimum and safe working right from the start. NOTICE

The Oerlikon Leybold Vacuum **TURBO.DRIVE 400** has been designed for safe and efficient operation when used properly and in accordance with these Operating Instructions. It is the responsibility of the user to carefully read and strictly observe all safety precautions described in this section and throughout the Operating Instructions. The TURBO.DRIVE **must only be operated in the proper condition and under the conditions described in the Operating Instructions**. It must be operated and maintained by trained personnel only. Consult local, state, and national agencies regarding specific requirements and regulations. Address any further safety, operation and/or maintenance questions to our nearest office.

DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

CAUTION indicates a potentially hazardous situation which, if not avoided, could result in minor or moderate injury.



# **Safety Information**



NOTICE is used to notify users of installation, operation, programming or maintenance information that is important, but not hazard related.

We reserve the right to alter the design or any data given in these Operating Instructions.

The illustrations are not binding.

Retain the Operating Instructions for further use.



WARNING

#### Important Safety Information

The frequency converter must only be connected to power supplies which meet the requirements for functional extra low voltage with positive isolation in accordance with IEC 364 (VDE 0100, Part 410, or local regulations) (PELV).

During operation the frequency converter may attain temperatures up to 75 °C. We recommend that the unit be installed so that it can not be touched inadvertently.

Inside the unit there is the risk of suffering burns from hot components.



The pump may be operated only with a suitable frequency converter and suitable connecting cables.

Ensure correct polarity.

Route all cables so as to protect them from damage.

Disconnect and connect the cable connections only while the pump is turning no longer (green status LED off) and with the mains power switched off (yellow power LED off). Otherwise there is the risk of damaging the TURBO.DRIVE 400.

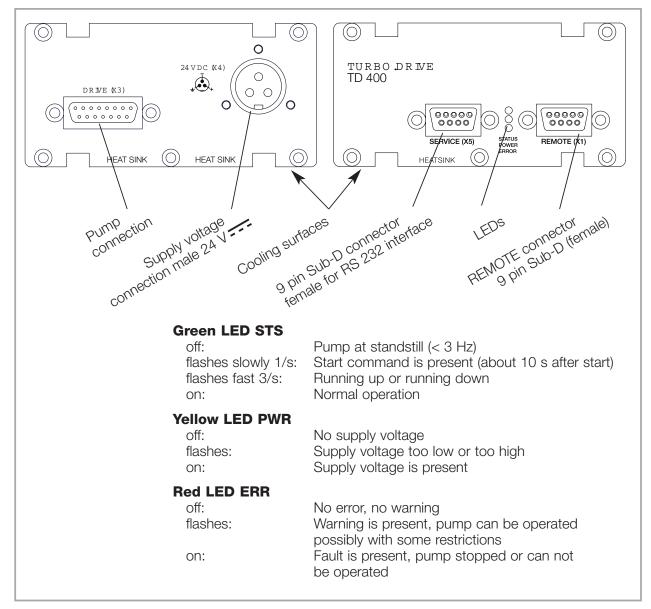


Fig. 1.1 TURBO.DRIVE 400, front and rear side

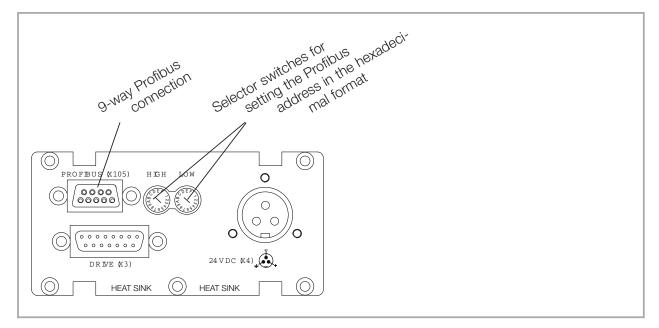


Fig. 1.2 Rear side of TURBO.DRIVE 400 with additional Profibus interface

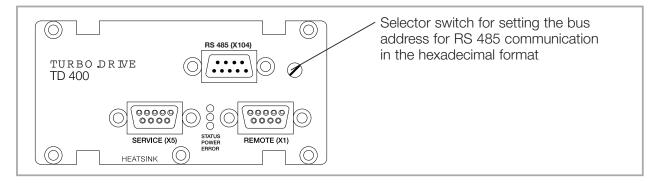


Fig. 1.3 Front side of TURBO.DRIVE 400 with additional RS 485 interface

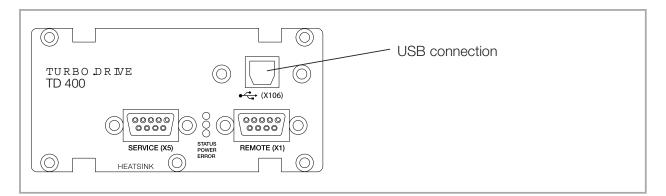


Abb. 1.4 FTURBO.DRIVE 400 front panel with additional USB interface

#### 1 Description

#### **1.1 Design and function**

The TURBO.DRIVE 400 supplies power to the TW and SL series turbomolecular pumps and is used to control their operation.

The TURBO.DRIVE 400 is either integrated in the pump or it is separate and linked to the pump by means of a connecting cable.

The TURBO.DRIVE 400 requires a supply voltage of 24 V DC. It is equipped with interfaces for programmable controls (REMOTE) and an optional interface for serial communication.

#### 1.2 Standard equipment

Included with the delivery are the DC connector Hirose HS16P-3, four moving nuts M4 for affixing the frequency converter and the Operating Instructions.

| <b>1.3 Technical data</b><br>Supply voltage<br>Residual ripple<br>< 3 %                            | 24 V (± 10%)   |
|--|--|
| Output<br>Voltage<br>Power<br>Frequency  | 0 - 24 V 3~<br>160 W<br>0 - 1500 Hz  |
| When operating a TW 300, TW 300 H,<br>SL 300<br>Nominal voltage<br>Max. power consumption<br>190 W | TW 220/150(/15) S,<br>24 V <del></del>   |
| Max. peak current, input side<br>Required power output from the pow                                | er supply $\geq 200 \text{ W}$   |
| When operating a TW 70 H, TW 250 S<br>Nominal voltage<br>Max. power consumption<br>140 W           | . SL 80<br>24 V <del></del>  |
| Max. peak current, input side<br>Required power output from the pow                                | $\begin{array}{r} 6 \text{ A DC} \\ \text{er supply} \geq 150 \text{ W} \end{array}$ |
| Max. length of the DC cable (shielded)<br>at 3 x 1.5 mm <sup>2</sup><br>at 3 x 2.5 mm <sup>2</sup> | 5 m<br>20 m  |
| Relay output rating  | 42 V, 0.5 A  |
| Ambient temperature<br>during operation<br>storage   | 5 - 45 °C<br>- 15 - + 70 °C  |
| Relative air humidity  | 5 to 85 %<br>non condensing  |
| Overvoltage category<br>Contamination grade  | I<br>2   |
| Temp. of the cooling surface<br>For Part Nos. 800073V0004  | 5 - 55 °C<br>5 - 50 °C   |
| Power consumption  | $\leq$ 20 W  |
| Type of protection   | IP 20  |
| Weight, approx.  | 0.7 kg   |

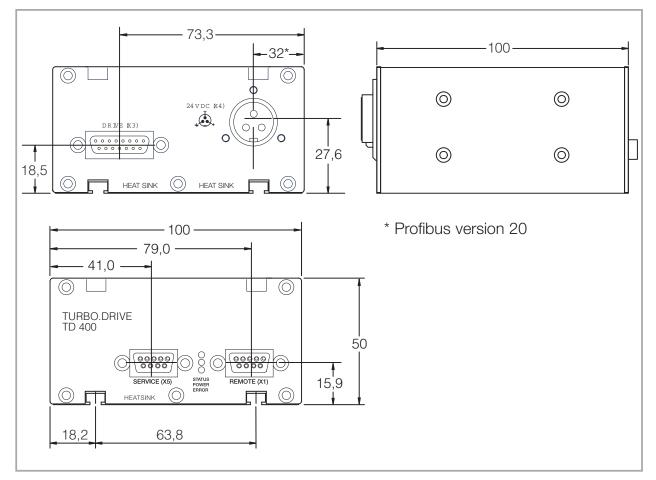
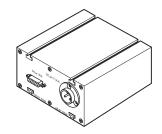
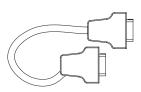


Fig. 1.5 Dimensional drawing for the frequency converter; dimensions in mm





#### 1.4 Ordering data

#### Frequency converter TURBO.DRIVE 400

| with RS 232 C interface | 800073V0002 |
|-------------------------|-------------|
| with RS 485 C interface | 800073V0003 |
| with Profibus interface | 800073V0004 |
| wiht USB interface      | 800073V0008 |

#### **Connecting cable pump - frequency converter**

| 1.0 m long | 152 47 |
|------------|--------|
| 2.5 m long | 864 49 |
| 3.0 m long | 864 40 |
| 5.0 m long | 864 50 |
|            |        |

#### 1.5 Accessories

#### **OEM** power supply (with screw terminals)

SITOP 24 V / 10 A (120/230 VAC / 50/60 Hz) 152 50 supplies the TURBO.DRIVE 400 with 24 V DC other power supplies on request

other power supplies on request

#### 24 V DC cable (TURBO.DRIVE 400 – OEM power supply)

| •    |            |
|------|------------|
| 3 m  | 200 12 732 |
| 5 m  | 200 12 733 |
| 10 m | 200 12 734 |
| 20 m | 200 12 735 |
|      |            |

#### Mains cable for power supply, 2 m long

| with EURO plug     | 800102V0001 |
|--------------------|-------------|
| with US plug 5-15P | 800102V1001 |



### Power supply unit - plug and play TURBO.POWER 300

800100V0002

- supplies the TURBO.DRIVE 400 with 24 V DC
- plug & play cables
- desktop unit or rack mountable

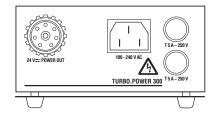
### 24V DC Power cable TURBO.DRIVE 400 – TURBO.POWER 300)

| 1 m  | 800094V0100 |
|------|-------------|
| 3 m  | 800094V0300 |
| 5 m  | 800094V0500 |
| 10 m | 800094V1000 |
| 20 m | 800094V2000 |

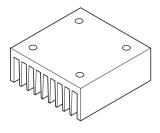
#### Mains cable for TURBO.POWER 300, 3 m long

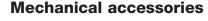
| with EURO plug     | 800102V0002 |
|--------------------|-------------|
| with US plug 6-15P | 800102V1002 |
| with UK plug       | 800102V0003 |

#### $\odot$ $\odot$ O START Power supply and control unit START 1 O NORMAL **TURBO.CONTROL 300** 800100V0001 O POWER ■ supplies the TURBO.DRIVE 400 with 24 V DC O ERROR plug & play cables desktop unit or rack mountable TURBO.CONTROL 300 with power switch ■ with start/stop switch for the turbomolecular pump remote control ■ status LEDs and status relays 24V DC Control cable (TURBO.DRIVE 400 - TURBO.CONTROL 300) 1 m 800091V0100 3 m 800091V0300 5 m 800091V0500 10 m 800091V1000 20 m 800091V2000 Mains cable for TURBO.CONTROL 300, 3 m long with EURO plug 800102V0002 with US plug 6-15P 800102V1002 with UK plug 800102V0003









| Plug for connector REMOTE with integra | ated        |
|--|-------------|
| ON/OFF switch for the pump             |             |
| (Sub-D plug, 9 way)                    | 152 48      |
| Heat sink for frequency converter      | 800110V0001 |

Top hat rail adaptor (mounting aid for TURBO.DRIVE 400 and TURBO.POWER 300) 800110V0003

#### Accessories for serial interfaces

USB driver: the Windows driver can be downloaded from www.oerlikon.com after selecting menu item www.oerlikon.com in the menu Oerlikon Leybold Vacuum  $\rightarrow$  Documentation  $\rightarrow$  Download Software

PC software "Turbo.Drive Server" for Windows 95 and higher, CD-ROM

Display, change, save and compare parameter lists

Integration of customer's software
 Record parameter data

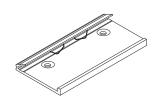
800110V0102

(new parameter library for TURBO.DRIVE 400 is required, please ask us for a quotation)

The software can also be downloaded from

www.oerlikon.com in the menu Oerlikon Leybold Vacuum  $\rightarrow$  Documentation  $\rightarrow$  Download Software

GSD file for Profibus DP upon request The software can also be downloaded from www.oerlikon.com in the menu Oerlikon Leybold Vacuum  $\rightarrow$  Documentation  $\rightarrow$  Download Software



#### 2 Installation

#### 2.1 Conforming utilization

The TURBO.DRIVE 400 supplies power to the TW series turbomolecular pumps and is used to control their operation.

The TURBO.DRIVE 400 is suited for operation of the following pumps:

- TURBOVAC TW 70 H
- TURBOVAC TW 220/150 S, TW 220/150/15 S, TW 400/300/25 S
- TURBOVAC TW 250 S
- TURBOVAC TW 290 H
- TURBOVAC TW 300, TW 300 H
- TURBOVAC SL 80, SL 300

Other pumps may only be operated after approval from Oerlikon Leybold Vacuum or if the operation of such pumps is expressly permitted in the Operating Instructions for the specific pump.

The TURBO.DRIVE may only be operated with power supply units which meet PELV (Safety Extra Low Voltage) requirements.

The TURBO.DRIVE must only be opened by certified Oerlikon Leybold Vacuum Service Centres. Opening by unauthorised personnel voids warranty.

#### 2.2 Operating environment

See also Chapter 1.3 Technical Data.

Places of installation up to 1000 m above sea level (3300 ft) are possible without restrictions. At altitudes over 1000 m heat dissipation by the ambient air is impaired. Please consult us.

If the TURBO.DRIVE 400 has been integrated in the pump, it is cooled by the pump.

As to the cooling requirements for the separately fitted TURBO. DRIVE see Fig. 2.1. The bottom side of the frequency converter must not be allowed to attain too high temperatures; see technical data.

Max. magnetic induction levels are 15 mT, max. radioactive radiation spec. is  $10^5$  rad ( $10^3$  Gy).

The frequency converter must only be used in rooms within buildings. It must not be operated in explosive gas atmospheres.

The frequency converter and the connecting lines must be protected against exposure to sprayed and condensing water.



During operation the frequency converter may attain temperatures up to 75 °C. We recommend that the unit be installed so that it can not be touched inadvertently.

Owing to the small quantity of combustible material and the proven safety of the instrument by testing in accordance with EN 61010, the risk through fire and burning can almost completely be excluded.

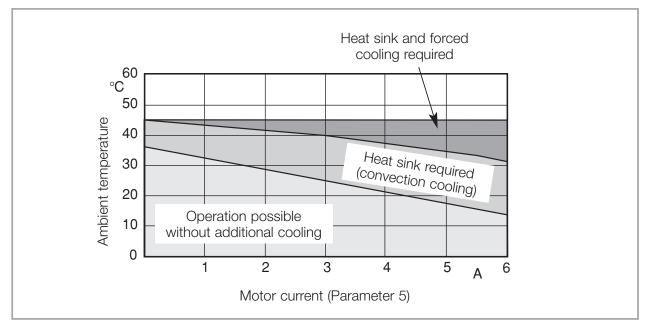


Fig. 2.1 Cooling requirements for the TURBO.DRIVE 400 when fitted separately

#### 2.3 Mounting the frequency converter

The frequency converter may be affixed with the aid of the enclosed M4 sliding nuts. The bottom side of the frequency converter must be cooled sufficiently.

Ensure an adequate supply and discharge of cooling air.

For special requirements please contact us.

#### 2.4 Connecting the pump

In the case of a separately fitted TURBO.DRIVE 400 connect the pump using the connecting cable.

The pump may be operated only with a suitable frequency converter and suitable connecting cables.

Route all cables so as to protect them from damage.

Disconnect and connect the cable connections only while the pump is turning no longer (green status LED off) and with the mains power switched off (yellow power LED off). Otherwise there is the risk of damaging the TURBO.DRIVE 400.

#### 2.5 Connecting the power supply



NOTICE

The frequency converter must only be connected to power supplies which meet the requirements for functional extra low voltage with positive isolation in accordance with IEC 364 (VDE 0100, Part 410, or local regulations) (PELV).

The power supply must meet the requirements given in Section 1.3. Peak currents in the kHz range may be present on the DC side. The power supply should have a current limiter of the current regulated type.

Connect the frequency converter to the 24 V DC power supply or to the TURBO.CONTROL 300 or to the TURBO.POWER 300 via the 24 V DC cable.

NOTICE

Ensure correct polarity. Pin 1 + 24 VDC Pin 2 0 V

Pin 2 0 V Pin 3 GND

The frequency converter is equipped with an internal 8 AT (slow blow) fuse. It can only be replaced by Oerlikon Leybold Vacuum staff.

Connect the power supply to the mains.



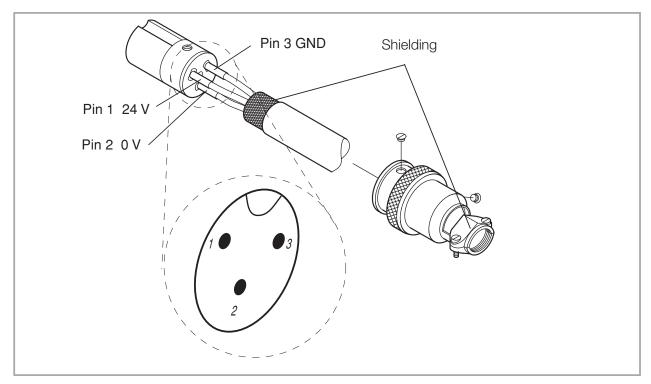


Fig. 2.2 Pin assignment of the DC connector (X4) Model Hirose HS16P-3

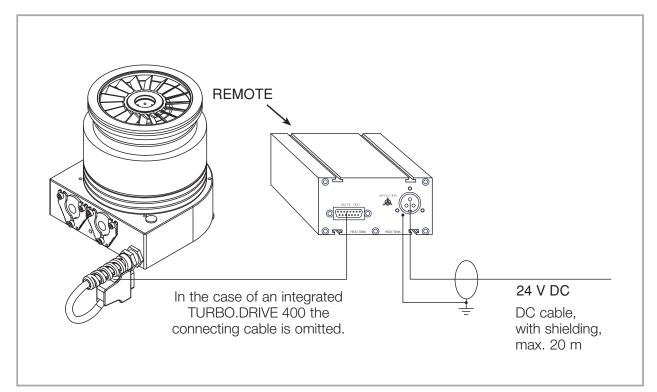
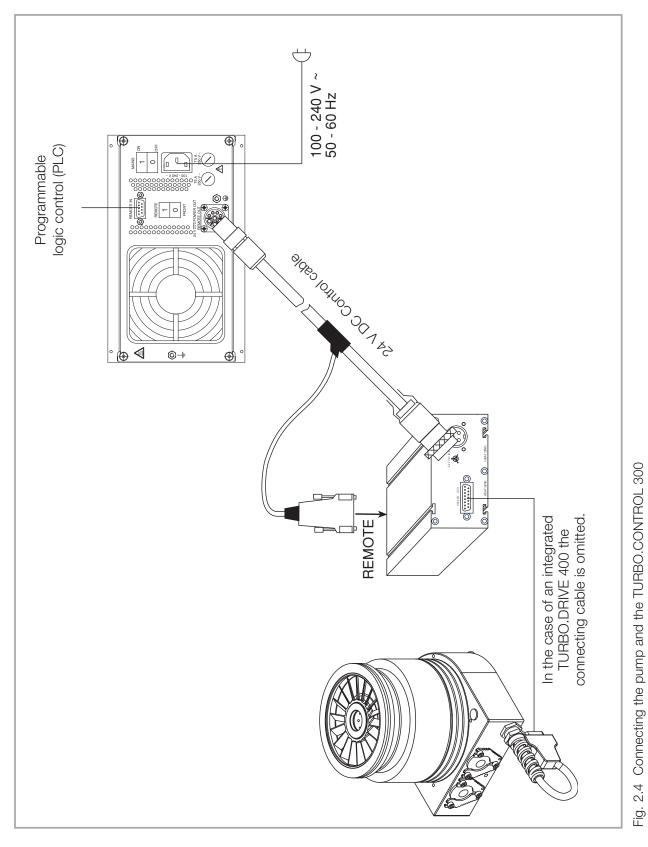
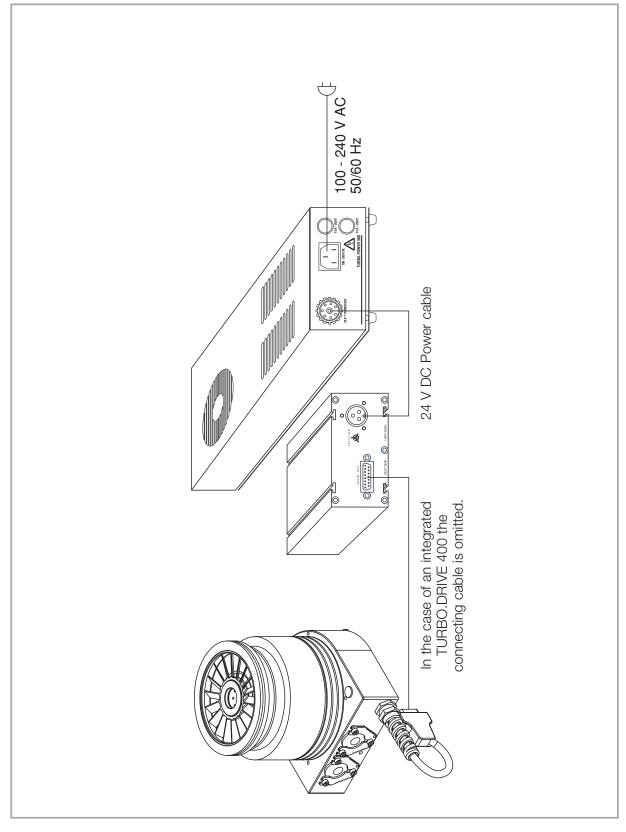
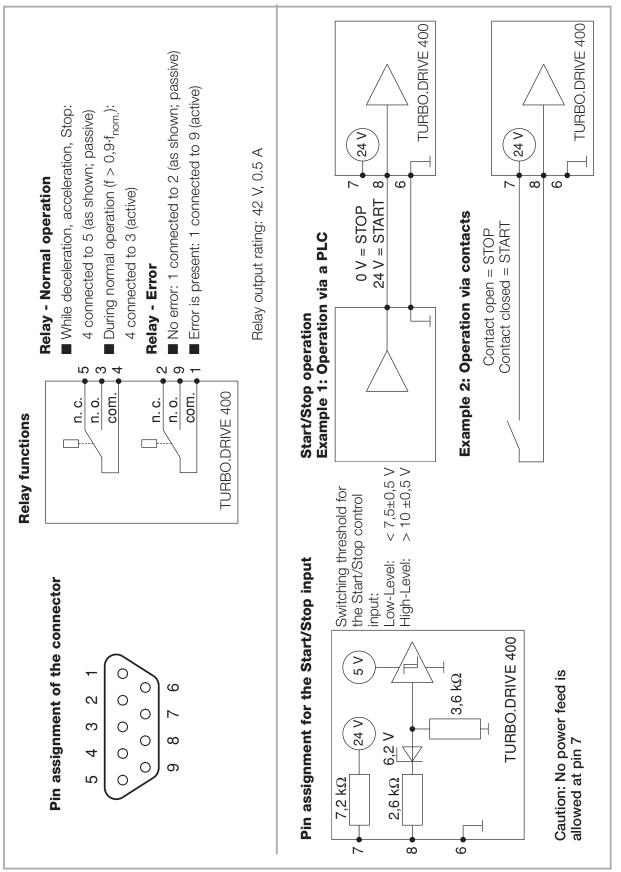


Fig. 2.3 Connecting the pump and the power supply







| status |
|--------|
| Relay  |

2.6

| Input                    | Input data / status | atus   |                     |                | Output data                  | data           |                          |                       | Operating mode   |
|--------------------------|---------------------|--|---------------------|----------------|------------------------------|----------------|--------------------------|-----------------------|--|
| Start/<br>stop<br>signal | Pump<br>rotating    | Normal<br>frequency<br>≥ 90% of<br>setpoint<br>frequency                             | Error is<br>present | Motor<br>drive | Relay<br>NORMAL<br>OPERATION | Relay<br>ERROR | LED<br>STATUS<br>(green) | LED<br>ERROR<br>(red) |  |
| Stop                     | ou                  | ou   | ou                  | off            | passive                      | passive        | off                      | off                   | Pump not operating   |
| Stop                     | yes                 | ОЦ   | ou                  | off            | passive                      | passive        | flashes                  | off                   | Pump is decelerating   |
| Stop                     | yes                 | yes  | ou                  | off            | passive                      | passive        | flashes                  | off                   | Just after stop; pump was in the normal operating mode before that |
| Start                    | ОЦ                  | ОЦ   | ou                  | uo             | passive                      | passive        | off                      | off                   | Just after start   |
| Start                    | yes                 | ОЦ   | ou                  | uo             | passive                      | passive        | flashes                  | off                   | Pump is accelerating   |
| Start                    | yes                 | yes  | ou                  | uo             | active                       | passive        | green                    | off                   | Pump is in the normal operating mode                               |
| Stop                     | ОП                  | ОЦ   | yes                 | off            | passive                      | active         | off                      | red                   | Error is present; pump is at standstill                            |
| Stop                     | yes                 | OL   | yes                 | off            | passive                      | active         | flashes                  | red                   | Error is present; pump is decelerating                             |
| Stop                     | yes                 | yes  | yes                 | off            | passive                      | active         | flashes                  | red                   | Error has just occurred  |
| Start                    | оц                  | OU   | yes                 | off            | passive                      | active         | off                      | red                   | Error is present; pump is at standstill                            |
| Start                    | yes                 | OU   | yes                 | off            | passive                      | active         | flashes                  | red                   | Error is present; pump is decelerating                             |
| Start                    | yes                 | yes  | yes                 | off            | passive                      | active         | flashes                  | red                   | Error has just occurred  |
| Other mo                 | des are no          | Other modes are not possible; they indicate a failure affecting the TURBO.DRIVE 400. | hev indicat         | te a failu     | re affecting th              | Je TURBO.      | DRIVE 400.               |                       |  |

#### 3 Operation

#### 3.1 Start-up

The TURBO.DRIVE 400 offers the possibility of gently running in pumps which were not operated for a period between 6 and 12 months.

For this set the parameter P119 "Bearing run-in function" to 1; thereafter start this function through the start command.

All three LEDs will flash rapidly, during acceleration the green LED flash more slowly.

The run can be cancelled by revoking the start command. Pausing is not possible.

After a completed run-in the pump stops. The LEDs continue to flash.

Parameter 119 remains set after the run and needs to be set manually to 0.

In all, the entire bearing run-in process may take up to 4 hours.

Turbomolecular pumps which were not operated for a period of over 12 months should be returned to us. For more information on this please contact your local sales partner.

#### 3.2 Interfaces

The frequency converter has a RS 232 interface as standard (SERVICE X5) and is optionally equipped with serial interfaces:

■ RS 485 C



USB

The TURBO.DRIVE 400 is configured through the parameters according to the parameter list. Pxxx denotes parameter value xxx.

The PC software "TURBO.DRIVE Server" allows convenient access by the user to the parameters of the frequency converter. It can be downloaded from www.oerlikon.com in the menu Oerlikon Leybold Vacuum  $\rightarrow$  Documentation  $\rightarrow$  Download Software.

#### Interfaces priority level

The optional interface has the highest priority level, followed by the Service interface X5. The Remote input X1 has the lowest priority level. See also parameter 179 in Section 3.2.4.

#### Applications which can be implemented with the aid of the serial interface:

| Application  | Benefits to the customer   | How to do it   |
|--|--|--|
| Networking of several pumps<br>and other equipment   | Savings relating to the costs for signalling cables  | With Field Bus systems like<br>Profibus  |
| Automation   | Savings related to repetitive manual work  | For example by a control computer  |
| Avoidance of warnings and<br>warnings before overload<br>operation and early detection<br>of a failing pump        | <ul> <li>Precise planning for<br/>maintenance</li> <li>Improved reliability of sensitive<br/>production processes in a<br/>vacuum</li> </ul> | <ul> <li>Monitoring of:</li> <li>Motor current P5</li> <li>Ball bearing temperature</li> <li>P125 or P127</li> <li>Motor temperature P7</li> <li>Frequency converter<br/>temperature P11</li> </ul>                    |
| Standby operation  | <ul> <li>Extending the service life<br/>for the ball bearings</li> <li>Cutting energy consumption</li> </ul>                                 | Reducing the rotor's frequency through P24   |
| Troubleshooting  | Quick analysis of problems   | Reading of error memories<br>P171, P174 and P176:<br>error code, speed,<br>operating hours for error   |
| Slow pressure control by changing the pumping speed  | Dispensing with a flow controller  | Changing the rotor frequency through parameter 24  |
| Reducing the maximum motor current   | Cost savings through smaller<br>power supply units if peak loads<br>can be reduced   | With P139, motor current reduction factor  |
| Starting the pump with a delay if several consumers are connected to the same PSU                                  | Cost savings through smaller<br>power supply units<br>if peak loads can be reduced   | With P36, delay  |
| Frequency converter as a simple<br>pressure gauge, since<br>motor current is dependent<br>on the vacuum conditions | Dispensing with pressure gauges  | Monitor motor current P5;<br>second function for "Normal<br>Operation" relay: relay switches<br>as soon as the motor<br>current threshold is tripped.<br>Adjust second function: P29<br>Set motor current thresh.: P27 |
| Lowering the normal operation threshold  | Normal operating mode is attained faster, processes can be started faster  | Reduce frequency threshold through P25   |

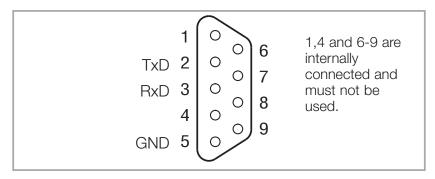


Fig. 3.1 Pin assignment for the socket at the frequency converter (female) SERVICE X5

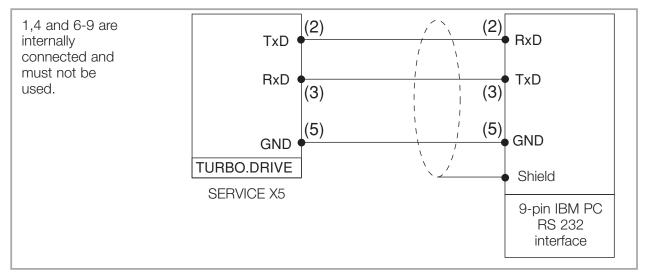


Fig. 3.2 Providing a RS 232 connection

#### 3.2.1 RS 232 C interface (SERVICE X5)

| Standards           | DIN 66020  |
|---------------------|--|
| Protocol            | acc. to VDI/VDE 3689   |
| Transmission rate   | 19200 baud   |
| Response delay      | default setting 10 ms<br>(parameter 180)                                 |
| Address range       | non-addressable  |
| Max. cable length   | 5 m  |
| Interface connector | 9 way Sub-D type,<br>socket on the instrument (female)<br>thread UNC4-40 |

Note: If on the controlling side an RS 232 interface in accordance with the PC standard with a 9-pin Sub-D male connector is present, then a straight through cable as shown in Fig. 3.2 may be used.

Refer also to Operating Instructions GA 05.281

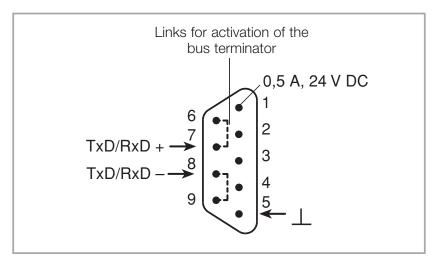


Fig. 3.3 Pin assignment for the socket at the frequency converter for RS 485 interface (male)

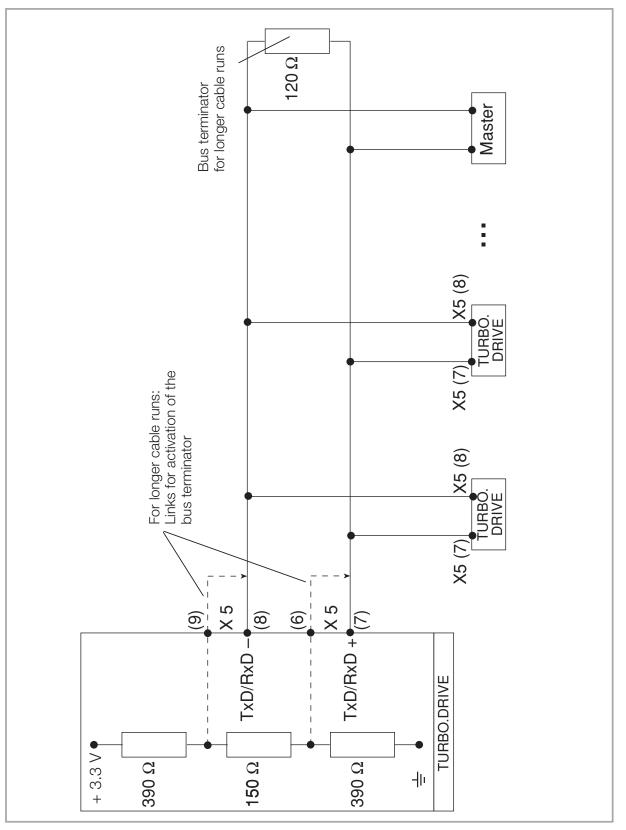
#### 3.2.2 RS 485 interface

| Standards   | ISO/IEC 8482, EIA 485  |
|---|--|
| Protocol  | acc. to VDI/VDE 3689   |
| Transmission rate                                     | 19200 baud fixed   |
| Response delay  | default setting 10 ms<br>(parameter 180)                               |
| Address range   | 0 15   |
| Max. cable length                                     | 50 m (with bus termination)  |
| Type of cable   | 2 wire twisted pair (twisted pair cable)                               |
| Differential voltage levels<br>(see also "Standards") | logic "0":<br>transmitter: 1.5 5 V<br>receiver: > 0.3 V                |
|   | logic "1":<br>transmitter: - 1,5 5 V<br>receiver: $\leq$ - 0,3 V       |
| Interface connector                                   | 9 way Sub-D type,<br>socket on the instrument (male)<br>thread UNC4-40 |

Note: After having changed the bus address through the rotary switch (see Fig. 1.3), the frequency converter must be switched off (yellow power LED off) and then on again so as to enable the new address setting.

Bus addresses over 15 can only be set via Parameter 37.

Refer also to Operating Instructions GA 05.281



#### 3.2.3 Profibus DP

The Profibus DP used has been defined in the standards EN 50170 and VDI/VDE 3689.

For more information on the Profibus system:

"The New Rapid Way to Profibus DP", Manfred Popp, Profibus Nutzerorganisation e.V., Haid-und-Neu-Str. 7 76131 Karlsruhe, Germany P/N: 4.072 www.profibus.com

Upon request we shall be pleased to provide detailed information on the hardware and the protocol used for the data.

Refer also to Operating Instructions GA 05.281

#### 3.2.4 USB Interface (X106)

| Transmission rate    | 19,200 Baud                        |
|----------------------|------------------------------------|
| Response delay time  | 10 ms (default)<br>(parameter 180) |
| Address range        | non-addressable                    |
| Maximum cable length | 5 m                                |
| Interface connector  | USB B                              |

Notice: the USB interface has been electrically separated from the converter and is supplied from the side of the USB host with a current of approximately 15 mA. Via the protection diode, separation with respect to 33 V is maintained.

#### 3.2.5 Parameter list

\* specific values for each pump; see table of pumps, Chapter 3.2.6; r = readable, w = writable

| No. | Designation                         | Min. | Max.  | Default | Unit  | r/w | Format | Description  |
|-----|-------------------------------------|------|-------|---------|-------|-----|--------|--|
| 1   | Converter type                      | 0    | 65535 | 0       |       | r   | u16    | 136 = Turbo.Drive 400  |
| 2   | Software version                    | 0    | 65535 | 10000   |       | r   | u32    | xx.yy: version, zz: correction index   |
| 3   | Actual frequency                    | 0    | 65535 | 0       | Hz    | r   | u16    | Actual rotor frequency   |
| 4   | Actual intermediate circuit voltage | 0    | 1500  | 30      | 0,1 V | r   | u16    | Actual intermediate circuit voltage of the converter   |
| 5   | Actual current                      | 0    | 150   | 0       | 0,1 A | r   | u16    | Actual motor current   |
| 6   | Actual electrical power             | 0    | 65535 | 0       | 0,1 W | r   | u16    | Actual drive input power   |
| 7   | Actual motor<br>temperature         | -10  | 150   | 0       | °C    | r   | i16    | Actual value of the motor temperature.   |
| 8   | Save data command                   | 0 b  | 65535 | 0       |       | /w  | i16    | A write command with any value saves temporary data into nonvolatile memory.   |
| 11  | Actual converter temperature        | -10  | 150   | 0       | °C    | r   | i16    | Actual heat sink temperature of the converter.   |
| 16  | Motor temperature warning threshold | 0    | 150   | *       | °C    | r   | i16    | Exceeding the motor temperature warning threshold results in a warning.  |
| 17  | Nominal motor<br>current            | 5    | 60    | *       | 0,1 A | r   | u16    | Maximum permissible motor current  |
| 18  | Maximum frequency                   | 750  | 1200  | *       | Hz    | r   | u16    | Highest permissible frequency  |
| 19  | Minimum frequency                   | 0    | 1200  | *       | Hz    | r   | u16    | Lowest permissible frequency   |
| 20  | Critical frequency                  | 0    | 1200  | *       | Hz    | r   | u16    | Minimum frequency level. When the<br>pump is accelerating this frequency<br>must be reached within the<br>maximum passing time (P183). |
| 23  | Pump type                           | 0    | 255   | *       |       | r   | u16    |  |
| 24  | Setpoint frequency                  | 0    | 1200  | *       | Hz    | r/w | u16    | Setpoint of the rotor frequency  |
| 25  | Normal operation                    | 35   | 99    | 90      | %     | r/w | u16    | Setpoint of the frequency dependent normal operation level   |

| No. | Designation   | Min.         | Max.        | Default         | Unit    | r/w | Format | Description  |  |  |  |  |  |  |
|-----|---|--------------|-------------|-----------------|---------|-----|--------|--|--|--|--|--|--|--|
| 27  | Current norm. oper.   | 5            | 60          | 20              | 0,1 A   | r/w | u16    | Motor current dependent normal<br>operation level; ; If P29[0] = 1:<br>Defines the normal operation level.<br>Normal operation if P5 <= P27<br>Parameter cannot be changed<br>during operation of the system |  |  |  |  |  |  |
| 29  | Relay function X1   | 0            | 8           | 0               |         | r/w | u16    | If required, special functions can be<br>assigned to the normal operation<br>and the error relay. Field 0  |  |  |  |  |  |  |
|     | <ul> <li>ecifies the function for normal operation:</li> <li>0 = Frequency dependent</li> <li>1 = Motor current dependent</li> <li>2 = Fieldbus controlled</li> <li>3 = Trigger current bearing temperature (P122)</li> <li>4 = Venting function (P247/P248)</li> <li>5 = Pump at standstill (f &lt; 3)</li> <li>6 = Start command is present</li> <li>7 = Ready for switch on (=STW Bit1)</li> <li>8 = No mains power failure or no generator operation (P303 Bit 4 =1 = generator operation)</li> <li>Field 1 specifies the function for the error relay:</li> <li>0 = Energised when an error is present</li> <li>1 = Deenergised when an error is present</li> <li>2 = Fieldbus controlled</li> </ul> |              |             |                 |         |     |        |  |  |  |  |  |  |  |
| 32  | 3 = Venting function<br>Max. run-up time  | 30           | 2000        | 720             | S       | r/w | u16    | Max. permissible time during which<br>the pump must attain the normal<br>operation threshold (P24*P25) with<br>the start signal present.   |  |  |  |  |  |  |
| 36  | Start delay time  | 0            | 255         | 0               | 0,1 min | r/w | u16    | Delays the start of the pump to<br>allow leadtime for the fore vacuum<br>pump for example.   |  |  |  |  |  |  |
| 38  | Start counter   | 0            | 65535       | 5 0             |         | r   | u16    | Increments each time when passing through the critical speed range.  |  |  |  |  |  |  |
| 37  | RS485 address 0 31 0 r/w u16 Parameterizable RS485 address;<br>The address is specified either<br>through the address switch or a value entered here provided the address switch is set to 0.<br>A change of this parameter setting will only be effective after the power<br>supply has been switched off and on.  |              |             |                 |         |     |        |  |  |  |  |  |  |  |
| 119 | Bearing run-in function   | 0<br>-in sea | 1<br>quence | 0<br>e specifie | -       |     |        | 0=deactivated<br>1=new pump type starts with<br>run-in sequence<br>ble without run-up time monitoring<br>I pumps)  |  |  |  |  |  |  |

| No. | Designation   | Min.      | Max. | Default | Unit  | r/w           | Format           | Description   |
|-----|---|-----------|------|---------|-------|---------------|------------------|---|
| 122 | Normal TMS  | 20        | 70   | 40      | °C    | r/w           | u16              | Switch-on temperature for fan when P29[0]=3. For P125 > P122 the normal operation relay is energised. |
| 125 | Bearing temperature   | -10       | 150  | 0       | °C    | r             | i16              | Actual value of the bearing temperature   |
| 126 | Bearing temperature warning threshold                                       | -10       | 150  | *       | °C    | r             | i16              | Exceeding the bearing temperature warning threshold results in a warning                              |
| 127 | Bearing temperature   | -10       | 150  | 0       | °C    | r             | i16              | Actual value of the bearing temperature   |
| 128 | Motor temperature<br>lower warning<br>threshold                             | -10       | 150  | 2       | °C    | r             | i16              | Falling below the motor temperature lower warning threshold results in a warning.                     |
| 131 | Motor temperature<br>lower error threshold                                  | 10<br>I - | 150  | -10     | °C    | r             | i16              | Falling below the motor temperature lower error threshold causes the pump to be switched off.         |
| 132 | Bearing temperature<br>error threshold                                      | -10       | 150  | *       | °C    | r             | i16              | Exceeding the bearing temperature error threshold causes the pump to be switched off.                 |
| 133 | Motor temperature<br>error threshold  | -10       | 150  | *       | °C    | r             | i16              | Exceeding the motor temperature error threshold causes the pump to be switched off.                   |
| 134 | Enable cooling fan<br>on turbopump  | 0         | 19   | 19      |       | r/w           | 116              | 0 = Cooling fan off<br>19 = Cooling fan on  |
| 139 | Current reduction<br>factor<br>e.g. for adaptation o<br>performance and inc |           |      | •       |       | r/w<br>plies. | u16<br>Note: val | Is used for the reduction of the maximum consumption current, ues < 100 reduce the pump               |
| 140 | Intermediate circuit current  | 0         | 150  | 0       | 0,1 A | r             | i16              | Actual average intermediate circuit current of the converter.   |
| 150 | Standby frequency   | 0         | 1200 | *       | Hz    | r/w           | u16              | Standby operation frequency setpoint  |
| 151 | Enable standby  | 0         | 1    | 0       |       | r/w           | u16              | 0 = normal speed (P24);<br>1 = standby speed (P150)   |

| No. | Designation   | Min.                             | Max.                                      | Default   | Unit  | r/w                      | Format                              | Description   |
|-----|---|----------------------------------|---|---|---|--------------------------|-------------------------------------|---|
| 171 | Error code memory   | 0                                | 65535                                     | 0   |   | r                        | u16                                 | Indexed parameter for storing the most recent 40 error codes.   |
|     |   | acce                             | essed v                                   | vith inde                                       |   |                          |                                     | eter with additional index number.<br>index 39. See Section 5   |
| 174 | Error rotor frequency   | 0                                | 65535                                     | 0   | Hz  | r                        | u16                                 | Actual speed, when error occurred.<br>Access analogously as for<br>parameter 171.                                   |
| 176 | Error operating hours   |                                  | 474836                                    | 0<br>647  | h   | r                        | u32                                 | Operating hours, when error<br>occurred. Access analogously as for<br>parameter 171.                                |
| 179 | Fallback PZD1   | 0                                | 65535                                     | 1024  |   | r/w                      | u16                                 | Response when cancelling the control rights or in the case of a   |
|     | communication betw<br>respective bus adapt<br>converter electronics | 10 ir<br>een c<br>ers p<br>is ca | n the co<br>converte<br>erform<br>pable c | ontrol wo<br>er and b<br>a cyclic<br>of detecti | ord of the<br>us adapt<br>commun<br>ing a cor | er (se<br>icatio<br>nmun | e also P1<br>n on the<br>ication in |   |
|     | The bits in parameter   | 179                              | represe                                   | ent an eo                                       | quivalent                                     | to the                   | e control                           | word in the USS protocol.   |
|     |   |                                  |   |   |   |                          |                                     | ntrol word (USS protocol for bus cation between converter and bus   |
|     |   | ol righ                          | its are r                                 | returned  |   |                          |                                     | ty level. All other bits are not relevant.<br>red to the other bits are run.  |
| 180 | Resp. delay time  | 0                                | 20  | 10  | ms  | r/w                      | u16                                 | Response delay time; Pause time between received and transmitted  |
| _   | USS protocol string of We recommend not t                           |                                  |   | -   |   |                          |                                     |   |
| 182 | Watchdog timer USS  |                                  | 65535                                     |   | 0,1 s   | r/w                      | u16                                 | Delay when cancelling the control rights of the bus adapter   |
|     | and time-out in the c   | ase c                            | of a con                                  | nmunica   | tion inter                                    | ruptio                   | n                                   |   |
|     | an interruption in the  | comr<br>elling                   | munica<br>bit 10 d                        | tion betv                                       | veen bus                                      | adap                     | oter and o                          | trol word of the USS protocol or when<br>converter and electronics is detected.<br>on the communication side of the |
|     | Value 0.0: Indefinite t   | ime c                            | lelay. In                                 | this way  | y a chang                                     | ge of                    | the contr                           | ol right is inhibited.  |
|     | Values 0.16553.5:   | A cha                            | ange in                                   | the cont  | trol right                                    | corres                   | sponding                            | to the setting of parameter 179 is  |

Values 0.1 ..6553.5: A change in the control right corresponding to the setting of parameter 179 is only effected after the time span defined through parameter 182 has elapsed.

| No. | Designation               | Min.    | Max.   | Default  | Unit   | r/w | Format | Description   |
|-----|---------------------------|---------|--------|----------|--------|-----|--------|---|
| 183 | Max. passing time         | 0       | 1800   | 500      | S      | r   | u16    | Max. permissible time during which<br>the pump must - with the start signal<br>present - have passed through the<br>critical speed range between 60 Hz<br>and P20.                                    |
| 184 | Converter operating hours | 0<br>21 | 474836 | 0<br>647 | 0,01 h | r   | u32    | Counts the operating hours of the converter during active pump operation.   |
| 227 | Warning bits 1            | 0       | 65535  | 0        |        | r   | u16    | Active warnings described bit per bit.<br>See Section 3.2.6.  |
| 247 | Vent on frequency         | 0       | 1200   | 300      | Hz     | r/w | u16    | Frequency at which the venting valve<br>shall be switched on in the event of a<br>mains power failure. Power failure<br>venting can be enabled through<br>P240.                                       |
| 248 | Vent off frequency        | 0       | 1200   | 5        | Hz     | r/w | u16    | Frequency at which the venting valve<br>shall be switched off in the event of a<br>mains power failure. Power failure<br>venting can be enabled through<br>P240.                                      |
| 249 | Generator operation       | 0       | 1      | 1        |        | r/w | u16    | 0 = inactive<br>1 = active  |
| 303 | Actual operating status   | 0       | 65535  | 0        |        | r   | u16    | Bit 0: Normal operation<br>Bit 1: Ready for switch on<br>Bit 2: Speed is increasing<br>Bit 3: Speed is dropping<br>Bit 4: Generator operation<br>Bit 5: Standby<br>Bit 6: reserved<br>Bit 7: reserved |

| No. | Designation   | Min.   | Max. De                | fault | Unit           | r/w    | Format     | Description   |
|-----|---|--------|------------------------|-------|----------------|--------|------------|---|
| 312 | Catalog number<br>of converter                      | 0      | 127<br>[8000×          |       | :CHAR<br>)x]   | r      | u16        | Catalogue number of the converter.<br>One ASCII char per index.                           |
| 313 | Product name<br>(Index 010 usable)                  | 0<br>0 | 127 [TD <u></u><br>127 |       | :CHAR<br>:CHAR | r<br>r | u16<br>u16 | Product name of the converter.<br>One ASCII char per index.<br>Only for DeviceNet purpose |
| 315 | Serial number of<br>converter<br>(Index 010 usable) | 0      | 127<br>[xxxxx          | xxxxx | :CHAR<br>x]    | r      | u16        | Serial number of the converter.<br>One ASCII char per index.                              |
| 918 | Act. Profibus addr.                                 | 0      | 65535                  | 0     |                | r      | u16        | Active Profibus address   |
| 947 | Current error numbe                                 | r O    | 65535                  | 0     |                | r      | u16        | Currently pending error. See<br>Chapter 5 Troubleshooting.                                |

#### 3.2.6 Specific parameter data for the pumps

| Type<br>pur | np designation             | Nominal<br>and setpoint<br>frequency<br><b>P18 / P24</b> | frequency | Minimum<br>frequency<br>level<br><b>P20</b> | Max.<br>motor<br>current<br><b>P17</b> | Max.<br>bearing<br>temp.<br><b>P132</b> | Max.<br>motor<br>temp.<br><b>P133</b> | Bearing<br>temp.<br>warning<br>threshold<br><b>P126</b> | Motor<br>temp.<br>warning<br>threshold<br><b>P16</b> |
|-------------|----------------------------|--|-----------|---|--|---|---------------------------------------|---|--|
| FZJ         | •                          | F10/F24  | FIJ       | F20   | F1/                                    | F132                                    | F133                                  | F120  | FIU  |
| 0           | TW 220/150<br>TW 220/150/1 | 5 750  | 650       | 375   | 6.0                                    | 80                                      | 100                                   | 70  | 95   |
| 1           | TW 400/300/25              |  | 050       | 075   | 0.0                                    | 00                                      | 100                                   | 70  | 05   |
|             | TW 250/200/4               | 0 800  | 650       | 375   | 6,0                                    | 80                                      | 100                                   | 70  | 95   |
| 2           | TW 250S                    | 860  | 750       | 340   | 5.0                                    | 67                                      | 100                                   | 60  | 95   |
| З           | TW 70 H                    | 1200   | 910       | 340   | 5.0                                    | 67                                      | 90                                    | 60  | 85   |
| 4           | TW 290 H /<br>TW 300 /     |  |           |   |  |   |                                       |   |  |
|             | TW 300 H                   | 1000   | 890       | 375   | 5.0                                    | 80                                      | 63                                    | 70  | 58   |
| 5           | SL 80                      | 1200   | 910       | 340   | 5.0                                    | -                                       | 55                                    | -   | 53   |
| 6           | SL 300                     | 1000   | 890       | 375   | 5.0                                    | -                                       | 56                                    | -   | 54   |

| Type<br>pur<br><b>P23</b> | np designation                     | Standby frequency<br>[Hz]<br><b>P150</b> |  |
|---------------------------|------------------------------------|--|--|
| 0                         | TW 220/150<br>TW 220/150/15        | 700                                      |  |
| 1                         | TW 400/300/25S<br>TW 250/200/40    | 700                                      |  |
| 2                         | TW 250S                            | 800                                      |  |
| 3                         | TW 70 H                            | 910                                      |  |
| 4                         | TW 290 H /<br>TW 300 /<br>TW 300 H | 960                                      |  |
| 5                         | SL 80                              | 910                                      |  |
| 6                         | SL 300                             | 960                                      |  |

#### Run-in sequence, bearing run-in function

| Type of<br>pump<br><b>P23</b> | Pump<br>designation                | Run-in<br>speed 1<br>[Hz] | Run-in<br>time 1<br>[s] | Run-in<br>speed 2<br>[Hz] | Run-in<br>time 2<br>[s] | Run-in<br>speed 3<br>[Hz] | Run-in<br>time 3<br>[s] |  |
|-------------------------------|------------------------------------|---------------------------|-------------------------|---------------------------|-------------------------|---------------------------|-------------------------|--|
| 0                             | TW 220/150<br>TW 220/150/15        | 100                       | 3600                    | 300                       | 5400                    | 300                       | 5400                    |  |
| 1                             | TW 400/300/25S<br>TW 250/200/40    | 100                       | 3600                    | 300                       | 5400                    | 300                       | 5400                    |  |
| 2                             | TW 250S                            | 100                       | 3600                    | 300                       | 5400                    | 500                       | 5400                    |  |
| 3                             | TW 70 H                            | 180                       | 3600                    | 350                       | 5400                    | 600                       | 5400                    |  |
| 4                             | TW 290 H /<br>TW 300 /<br>TW 300 H | 200                       | 3600                    | 430                       | 5400                    | 580                       | 5400                    |  |
| 5                             | SL 80                              | 180                       | 3600                    | 430                       | 5400                    | 580                       | 5400                    |  |
| 6                             | SL 300                             | 200                       | 3600                    | 430                       | 5400                    | 580                       | 5400                    |  |

| P227,<br>Bit | Designation                             | Meaning  | Possible cause                     | Remedy   |
|--------------|---|--|------------------------------------|--|
| 0            | Motor tempe-<br>rature war-<br>ning     | The motor<br>temperature<br>has passed the<br>warning thres-     | Forevacuum pres-<br>sure too high. | Check the ultimate pres-<br>sure of the backing pump<br>and install a bigger<br>backing pump if req. |
|              |   | hold   | Gas flow too high                  | Seal leak, check process   |
|              |   |  | Fan defective                      | Replace fan  |
|              |   |  | Water cooling switched off         | Switch on water cooling  |
| 1            | Converter<br>temperature                | Overtempera-<br>ture at the                                      | Ambient temperature too high       | Ensure max. ambient temperature of 45°C  |
|              | warning                                 | power output<br>stage or within<br>the frequency<br>converter    | Poor cooling                       | Improve cooling  |
| 2            | Bearing over-<br>temperature<br>warning | The permissi-<br>ble warning<br>threshold for<br>the bearing     | Forevacuum pres-<br>sure too high. | Check the ultimate pres-<br>sure of the backing pump<br>and install a bigger<br>backing pump if req. |
|              |   | temperature<br>was exceeded.                                     | Gas flow too high                  | Seal leak, check process   |
|              |   |  | Fan defective                      | Replace fan  |
|              |   |  | Water cooling switched off         | Switch on water cooling  |
| 3            | Motor under-<br>temperature             | The minimum permissible  | Ambient temperature too low        | Ensure min. ambient tem-<br>perature of 0°C  |
|              | warning                                 | motor tempe-<br>rature (warning<br>threshold) is<br>not reached. | Pump cooling too<br>high           | Reduce water cooling   |
| 4, 5         | not used                                |  |                                    |  |
| 6            | Overspeed<br>warning                    |  |                                    |  |

#### 3.2.7 Warning codes for parameter 227

| P227,<br>Bit   | Designation                        | Meaning  | Possible cause   | Remedy   |
|----------------|------------------------------------|--|--|--|
| 7, 8,<br>9, 10 | not used                           |  |  |  |
| 11             | Overload<br>warning                | The pump<br>speed has<br>dropped under<br>the normal                     | Forevacuum pres-<br>sure too high.   | Check the ultimate pres-<br>sure of the backing pump<br>and install a bigger<br>backing pump if req. |
|                |                                    | operation<br>threshold   | Gas flow too high  | Seal leak, check process   |
| 12,<br>13      | not used                           |  |  |  |
| 14             | Power supply<br>voltage<br>warning | Supply voltage<br>failure during<br>active opera-<br>tion of the<br>pump | Intermediate circuit<br>voltage too low or<br>maximum time for<br>generator operation<br>was exceeded. |  |
|                |                                    | P4 > Umax or<br>P4 < Umin  | DC power supply voltage below 24V  |  |
|                |                                    |  | Mains voltage failure  |  |
| 15             | Fan voltage<br>has failed          |  |  |  |

#### 3.3 Switching on

Switch on the DC power supply. The yellow LED at the frequency converter lights up.

Switch on the turbomolecular pump at the frequency converter

via pins 7 and 8 of the socket REMOTE (X1) (For example via a remote control or with the aid of the plug with integrated ON/OFF switch: see Section 1.5 Accessories).

■ by a start command via the interface.

The turbomolecular pump accelerates. The green LED flashes. When the pump reaches normal operation the green LED lights up permanently.

After a mains power failure the pump can run up automatically once more.

#### 3.4 Shutting down

Switch off the pump at the frequency converter.

- via contacts 7 and 8 of the socket REMOTE (X1).
- apply a stop command via the interface.
- for the power supply units offered or recommended by Oerlikon Leybold Vacuum switch off the DC voltage.

After switching off, the green status LED will flash until the rotor of the turbomolecular pump is at standstill. This may take several minutes. With the DC power supply off, the turbomolecular pump will act as a generator supplying the frequency converter with energy as indicated by the yellow power LED.

If a failure occurs the turbomolecular pump will be shut down automatically. The red LED at the frequency converter lights up.

To shut down the frequency converter, switch the pump off and wait until the rotor of the turbomolecular pump has arrived at standstill (green status LED off).

Then switch the mains power off and wait until the yellow power LED is off. Then only disconnect any cable connections.

#### 3.5 Emergency shut down

The emergency shutdown facility of a system controller must be capable of shutting the pump down as detailed in Chapter 3.3. The rotor of the turbomolecular pump may be stopped faster by venting the pump; for this refer to the Operating Instructions for the pump.

#### 3.6 Setting pumping speed and rotational speed

For the purpose of reducing the pumping speed of the pump because of application requirements or for other reasons it can make sense to reduce the rotational speed.

In order to permanently reduce the speed we recommend the following procedure:

With the aid of a Windows PC and the PC software "TURBO. DRIVE Server" change the setting for the parameter 24 "Setpoint frequency". The possible values for parameter 24 will depend on the type of pump connected. Parameter 18 "Nominal pump frequency" defines the maximum value and parameter 19 "Minimum setpoint frequency for the pump" defines the minimum value.

So as to retain the value saved for parameter 24 when switching the pump off, the parameter value needs to be saved permanently. For this enter any value (for example 1) for parameter 8. Thereafter changed parameters will be saved permanently.

Parameters which are typical for the specific type of pump (see Chapter 3.2.5) are reset to the factory defaults after having changed the type of pump and when switching on the power supply voltage again.

The rotational speed of the pump may be changed during operation also with the aid of a Windows PC and the PC software "TURBO.DRIVE Server".

However, we here recommend a PLC compliant solution with the aid of the Profibus. The speed can be set over the Profibus in two ways:

- by changing parameter 24 within the limits defined by parameters 19 and 18 or
- by transfer as the main setpoint (for this also refer to VDI/VDE 3689).

#### 3.7 Operation at reduced current

Not all applications require that the TURBO.DRIVE 400 be operated at its maximum current. Operation at reduced current will allow operation off a smaller power supply unit or to operate two or more turbomolecular pumps off a power supply unit which in practice is just not strong enough to supply the maximum current for several connected pumps. However, this will increase the run up time, and the maximum gas throughput and backing pressure specifications are reduced.

For this proceed as follows:

With the aid of a Windows PC and the PC software "TURBO. DRIVE Server" change the setting for the parameter 139 "Current reduction factor". The possible values for parameter 139 can be varied within the limits of 30 to 100 % of parameter 17 (current dependents on the type of connected pump. The newly entered current reduction factor will only be active after switching off and on again.

So as to retain the value saved for parameter 139 when switching the pump off, the parameter value needs to be saved permanently. For this enter any value (for example 1) for parameter 8. Thereafter changed parameters will be saved permanently.

# **3.8 Changing the frequency dependent normal operation level**

Depending on the quality of the vacuum which needs to be provided by the turbomolecular pump it may make sense to reduce the frequency dependent normal operation threshold, so that the ready status can be attained faster by the vacuum system. The factory default of 90 % represents a good compromise so that a change will hardly ever be required.

For this proceed as follows:

With the aid of a Windows PC and the PC software "TURBO. DRIVE Server" change the setting for the parameter 25 "Frequency dependent normal operation level". The possible values for parameter 25 can be varied within the limits of 35 to 99 % of parameter 24 (nominal speed depends on the type of connected pump).

So as to retain the value saved for parameter 25 when switching the pump off, the parameter value needs to be saved permanently. For this enter any value (for example 1) for parameter 8. Thereafter changed parameters will be saved permanently.

## **3.9 Changing the maximum permissible run up time**

In vacuum systems at a high backing pressure or with increased quantities of gas during the run up phase, the run up time for the turbomolecular pump may be longer. This will then cause the frequency converter to output an error message,

The maximum permissible run up time is changed as follows:

With the aid of a Windows PC and the PC software "TURBO. DRIVE Server" change the setting for the parameter 32 "Maximum run up time". The possible values for parameter 32 can be varied within the limits of P183 to 2000 seconds. The default setting is 720 seconds. As a rule, no value below 720 seconds should be entered as this would give rise to unnecessary error messages. If a significantly higher value than 720 seconds is required, this may indicate that the turbomolecular pump is being overloaded. For this reason in such a case the temperature data from the frequency converter and the turbomolecular pump (parameter 7 = motor temperature, 11 = frequency converter temperature, 125/127 bearing temperature) should be specially monitored during application trials.

So as to retain the value saved for parameter 32 when switching the pump off, the parameter value needs to be saved permanently. For this enter any value (for example 1) for parameter 8. Thereafter changed parameters will be saved permanently.

#### 3.10 Changing the start delay time

Generally it will make sense to let the turbomolecular pump run up immediately after applying the start command. However when operating two or more turbomolecular pumps off a single power supply unit, it may make sense to start the pumps one after the other. One way of achieving this is to enter a start delay time differing from 0.

To set up the start delay time proceed as follows:

With the aid of a Windows PC and the PC software "TURBO. DRIVE Server" change the setting for the parameter 36 "Start delay time". The possible values for parameter 36 can be varied within the limits of 0 to 25.5 minutes (0 to 255).

So as to retain the value saved for parameter 36 when switching the pump off, the parameter value needs to be saved permanently. For this enter any value (for example 1) for parameter 8. Thereafter changed parameters will be saved permanently.

#### 3.11 Selecting relay functions

See parameter 29.

#### 3.12 Reading the error memory

The TURBO.DRIVE 400 is capable of permanently saving up to 40 error events. The error codes are saved under parameter number 171. In addition to each error code the following is also saved:

- Rotor frequency at the point of time when the error event in parameter 174 occurred.
- The corresponding number of operating hours in parameter 176.

Access to each of the 40 groups of values is accomplished with the aid of an index value which needs to be stated besides the parameter number when accessing via the protocol in accordance with VDI / VDE 3689. The range of index numbers ranges from 0 to 39.

### Maintenance

#### 4 Maintenance

The frequency converter is maintenance free. Repairs must only be done by Oerlikon Leybold Vacuum.

If required clean the frequency converter of dust with a dry cloth.

When removing a defective frequency converter from an installation, please note the information given in Chapter 3.4.

During all work on the pump which is being driven by the frequency converter, the system must be protected against being switched on. For this disconnect the DC power supply.

#### 5 Troubleshooting

Before you start searching for the source of the problem, you should carry out a few simple checks:

Are the connections in good working order?

- Mains connection,
- DC power supply to the frequency converter,
- Connector cable between the frequency converter and the pump

Is the forevacuum pressure sufficient?

After having removed the cause for the error reset the error message at the TURBO.DRIVE:

In case of error code 8 by switching the mains power off.

■ In case of the other errors by applying a STOP signal via the socket REMOTE (X1) or a reset sequence via the serial interface or by switching the mains power off.

The error codes can only be read if a serial interface is present.

The following table has been provided as a guide when determining the causes of errors.

| Error<br>code | Designation                     | Meaning   | Possible Cause                      | Remedy  | Shut-<br>down |
|---------------|---------------------------------|---|-------------------------------------|---|---------------|
| 1             | Overspeed<br>warning            | The actual fre-<br>quency<br>exceeds the<br>setpoint by<br>over 10 Hz.        | Frequency con-<br>verter defective  | Contact Oerlikon<br>Leybold Vacuum<br>Service.  | no            |
| 2             | Pass through<br>time error      | The pump has<br>not reached<br>the minimum<br>speed after the<br>maximum run- | Forevacuum<br>pressure too<br>high. | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req.                       | yes           |
|               |                                 | up time has<br>elapsed.   | Gas flow too<br>high                | Seal leak, check pro-<br>cess   |               |
|               |                                 |   | Rotor blocked                       | Check if the rotor<br>turns freely. Contact<br>Oerlikon Leybold<br>Vacuum Service if the<br>rotor is damaged or<br>blocked. |               |
| 3             | Bearing<br>temperature<br>error | The maximum<br>permissible<br>bearing tem-<br>perature was<br>exceeded.       | Forevacuum<br>pressure too<br>high. | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req.                       | yes           |
|               |                                 |   | Gas flow too<br>high                | Seal leak, check pro-<br>cess   |               |
|               |                                 |   | Fan defective                       | Replace fan   |               |
|               |                                 |   | Water cooling switched off          | Switch on water cooling   |               |
| 4             | Short circuit<br>error          |   |                                     |   | yes           |
| 5             | Converter<br>temperature        |   | Ambient tempe-<br>rature too high   | Ensure max. ambient temperature of 45°C   | yes           |
|               | error                           |   | Poor cooling                        | Improve cooling   |               |

| Error<br>code | Designation                                | Meaning   | Possible Cause   | Remedy  | Shut-<br>down |
|---------------|--|---|--|---|---------------|
| 6             | Run-up time<br>error                       | The pump has<br>not reached<br>the normal<br>operating fre-<br>quency after | Forevacuum<br>pressure too<br>high.                            | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req. | yes           |
|               |  | the maximum<br>run-up time.   | Gas flow too<br>high   | Seal leak, check pro-<br>cess   |               |
| 7             | Motor tem-<br>perature error               | The motor<br>temperature<br>has exceeded<br>the shutdown<br>threshold.      | Forevacuum<br>pressure too<br>high.                            | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req. | yes           |
|               |  |   | Gas flow too<br>high   | Seal leak, check pro-<br>cess   |               |
|               |  |   | Fan defective  | Replace fan   |               |
|               |  |   | Water cooling switched off                                     | Switch on water cooling   |               |
| 8             | Pump error                                 | Pump couldn't<br>be identified or<br>no pump is<br>connected                | Pump not con-<br>nected correctly<br>to frequency<br>converter | Check connection<br>between pump and<br>frequency converter   | yes           |
|               |  |   | Hardware<br>defective  | Contact Oerlikon<br>Leybold Vacuum<br>Service   |               |
| 61            | Bearing tem-<br>perature war-<br>ning, top |   |  |   | no            |
| 82            | Fan voltage<br>has failed                  |   |  |   | no            |
| 83            | Motor tempe-<br>rature low<br>warning      |   |  |   | no            |

| Error<br>code | Designation                           | Meaning   | Possible Cause                      | Remedy  | Shut-<br>down |
|---------------|---------------------------------------|---|-------------------------------------|---|---------------|
| 84            | Motor over-<br>temperature<br>warning |   |                                     |   | no            |
| 101           | overload<br>warning                   | The pump<br>speed has<br>dropped under<br>the normal<br>operation | Forevacuum<br>pressure too<br>high. | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req. | no            |
|               |                                       | threshold   | Gas flow too<br>high                | Seal leak, check pro-<br>cess   |               |
| 103           | Supply<br>voltage<br>warning          | voltage circuit voltage   | DC supply vol-<br>tage below 24V    | Check the voltage at<br>the power supply<br>and if required set up<br>correctly                       | no            |
|               |                                       |   | Mains voltage<br>has failed         | Remedy the cause<br>for the mains power<br>failure  |               |
| 106           | overload error                        | The pump<br>speed has<br>dropped under<br>the minimum<br>speed    | Forevacuum<br>pressure too<br>high. | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req. | yes           |
|               |                                       |   | Gas flow too<br>high                | Seal leak, check pro-<br>cess   |               |
| 111           | Motor under-<br>temperature           | The minimum permissible   | Ambient tempe-<br>rature too low    | Ensure min. ambient temperature of 0°C  | yes           |
|               | error                                 | error motor tempe-<br>rature is not<br>attained.                  | Pump cooling<br>too high            | Reduce water cooing   |               |

| Error<br>code | Designation   | Meaning  | Possible Cause  | Remedy  | Shut-<br>down |
|---------------|---|--|---|---|---------------|
| 116           | Permanent<br>overload error   | The speed of<br>the pump has<br>dropped below<br>the normal<br>operation | Forevacuum<br>pressure too<br>high.                     | Check the ultimate<br>pressure of the<br>backing pump and<br>install a bigger<br>backing pump if req. | yes           |
|               | threshold and<br>has stayed<br>there for a lon-<br>ger period of<br>time. | Gas flow too<br>high   | Seal leak, check pro-<br>cess                           |   |               |
| 117           | Motor current<br>error  | Motor current<br>less than<br>nominal cur-<br>rent                       | Cable fault<br>Faulty<br>connector                      | Contact Oerlikon<br>Leybold Vacuum<br>Service   | yes           |
| 126           | Bearing tem-<br>perature sen-<br>sor error top                            | Bearing tem-<br>perature sen-<br>sor defective                           | Sensor defect-<br>ive, short circuit<br>or broken cable | Contact Oerlikon<br>Leybold Vacuum<br>Service   | yes           |
| 128           | Motor tem-<br>perature sen-<br>sor error                                  | Motor tem-<br>perature sen-<br>sor defective                             | Sensor defect-<br>ive, short circuit<br>or broken cable | Contact Oerlikon<br>Leybold Vacuum<br>Service   | yes           |
| 143           | Overspeed<br>error  |  |   |   | yes           |

| Error<br>code | Error                         | Possible Cause  | Remedy   | Shut-<br>down |
|---------------|-------------------------------|---|--|---------------|
| _             | Yellow power<br>LED is not on | No DC power   | Check cables and power supply  | _             |
|               |                               | DC power miswired   | Ensure correct polarity of the DC cable.   |               |
|               |                               | Frequency converter<br>defective  | <ul> <li>Replace frequency converter. The following may damage the freq. converter:</li> <li>Disconnection of the DC cable while the pump was still rotating</li> <li>Non-compliance with the note related to connecting several pump to a single power supply.</li> </ul> |               |
| div.          | Red LED<br>flashes            | Warning message.<br>See Section "3.2.6<br>Warning codes" for the<br>possible reasons of the<br>warning. | The pump can continue to<br>run, as long as operation<br>limits are only exceeded<br>for a short time. In case of<br>longer exceeding send<br>pump and frequency con-<br>verter to the OLV service.  | no            |

| Error<br>code | Error   | Possible Cause                             | Remedy                               | Shut-<br>down |
|---------------|---|--|--------------------------------------|---------------|
| _             | Turbomolecu-  | Interface protocol error                   | Use USS protocol.                    | _             |
|               | lar pump does<br>not start,<br>ERROR LED                            | No communication via the serial interface. | Connect bus as shown in Section 3.2. |               |
|               | does not light.   | REMOTE connector (X1) connected wrongly.   | Connect as shown in Fig.<br>2.6      |               |
|               |   | REMOTE and SERVICE connectors mixed up.    | Connect correctly.                   |               |
|               |   | Wrong Profibus address set.                | Set address between 0 and 126.       |               |
| -             | Turbomolecu-  | Rotor out of balance                       | Balance the rotor                    | no            |
|               | lar pump<br>produces loud<br>running noises<br>and vibra-<br>tions. | Bearing defective                          | Replace the bearing                  |               |

| Error<br>code | Error   | Possible Cause   | Remedy   | Shut-<br>down |
|---------------|---|--|--|---------------|
| _             | Turbomolecu-<br>lar pump does                   | Measurement instrument defective   | Inspect the measurement sensor   | no            |
|               | not reach ulti-<br>mate<br>pressure.            | Measurement sensors soiled   | Clean or replace the sensors   |               |
|               | procedie.                                       | Leaks at the equipment,<br>lines or the pump   | Check for leaks  |               |
|               |   | Pump soiled  | Clean the pump   |               |
|               |   | Forevacuum pump pro-<br>vides insufficient pumping<br>speed or ultimate pressure<br>which is too high. | Check the ultimate pres-<br>sure of the forevacuum<br>pump and install a higher-<br>capacity vacuum pump if<br>necessary |               |
|               |   | Frequency parameters programmed wrongly  | Check parameters.  |               |
| -             | Running<br>pump can not<br>be stopped<br>via X1 | Pump has been started via<br>the serial interface, the<br>interface controls the<br>pump               | Disconnect the DC supply<br>or connect serial interface<br>and stop via bus  | no            |

# Waste Disposal

#### 6 Waste Disposal

The equipment may have been contaminated by the process or by environmental influences. In this case the equipment must be decontaminated in accordance with the relevant regulations. We offer this service at fixed prices. Further details are available on request.

Contaminated parts can be detrimental to health and environment. Before beginning with any work, first find out whether any parts are contaminated. Adhere to the relevant regulations and take the necessary precautions when handling contaminated parts.

Separate clean components according to their materials, and dispose of these accordingly. We offer this service. Further details are available on request.

This product complies with the European Community Regulation 2002/95 (RoHS Restriction of Hazardous Substances).

#### Contamination



#### **RoHS compliance**

### **Notes**



### **EC Declaration of Conformity**

The manufacturer: Oerlikon Leybold Vacuum GmbH Bonner Strasse 498 D-50968 Cologne, Germany Tel.: +49 (0)221 347-0 info.vacuum@oerlikon.com

herewith declares that the products specified and listed below which we have placed on the market, comply with the applicable EC Council Directives. This declaration becomes invalid if modifications are made to the product without agreement of Oerlikon Leybold Vacuum GmbH. Compliance with the EMC Directives requires that the components are installed within a system or machine in a manner adapted to EMC requirements.

| Product designation: | Frequency | converter |
|----------------------|-----------|-----------|
|----------------------|-----------|-----------|

Type designation: TD400

Catalogue No.: 800073V0002 /03 /04 /05 /06 /07 /08

The product complies to the following European Council Directives:

- Directive on Low Voltage (2006/95/EC)
- Directive on Electromagnetic Compatibility (2004/108/EC)

#### The following harmonised standard has been applied:

• EN 61010-1 2001 incl correction 1 (11/2002) and correction 2 (1/2004)

Störaussendung / Festigkeit

- EN 55011 2007; class B
- EN 55011 2009-A1:2010; class B
- EN 61326-1 2006-05 class B
- EN 61000-6-3 2007 class B
- EN 61000-6-2 2005

**Documentation Officer:** 

Herbert Etges Tel.: +49(0)221 347-0 Fax: + 49(0)221 347-1250 E-Mail. documentation.vacuum@oerlikon.com Oerlikon Leybold Vacuum GmbH Bonner Strasse 498, D-50968 Cologne, Germany

Cologne, dated 2011 - 4-8

Dr. Monika Mattern-Klosson Head of Research & Development

Cologne, dated 2011 - 4 - 8

Harald Udelhoven Head of Quality Management



www.oerlikon.com

Oerlikon Leybold Vacuum GmbH Bonner Strasse 498 D-50968 Cologne Phone: +49-(0)221-347 0 Fax: +49-(0)221-347 1250 info.vacuum@oerlikon.com